

# Polynomial functors in Catlab

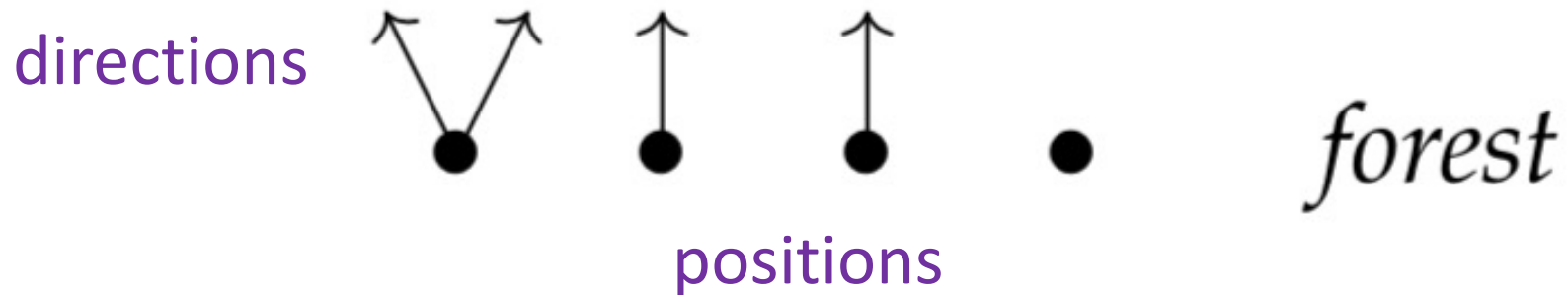
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ACT Conference 2021

<sup>1</sup> University of Maryland, College Park, <sup>2</sup> Johns Hopkins University Applied Physics Laboratory, <sup>3</sup> Stanford University,  
<sup>4</sup>University of Nottingham

# What is a polynomial functor (PF)?

$$y^2 + 2y + 1 \quad \textit{polynomial}$$

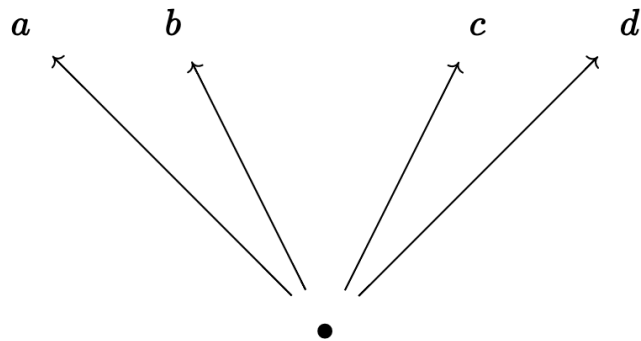


Sum of representable functors ( $y^A: \mathbf{Set} \rightarrow \mathbf{Set}, A \in \mathbf{Set}$ )

# PF for mode-dependent dynamical systems: An Intuition

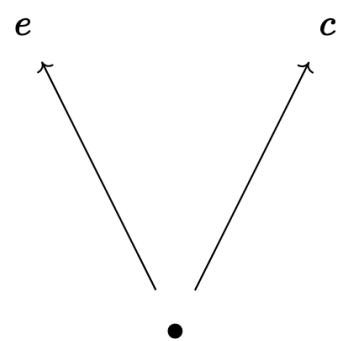
## Mode 1

- Option **a**
- Option **b**
- Option **c**
- Option **d**



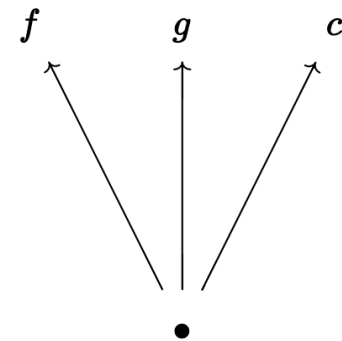
## Mode 2

- Option **e**
- Option **c**



## Mode 3

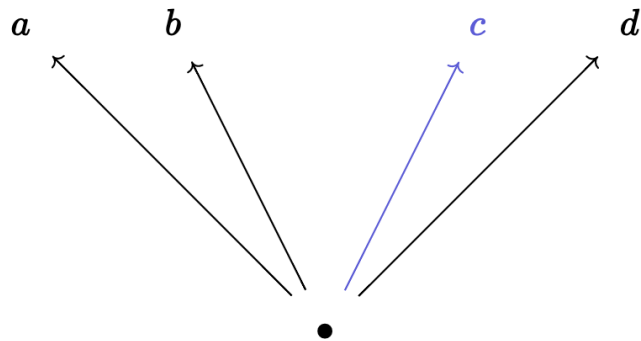
- Option **f**
- Option **g**
- Option **c**



# PF for mode-dependent dynamical systems: An Intuition

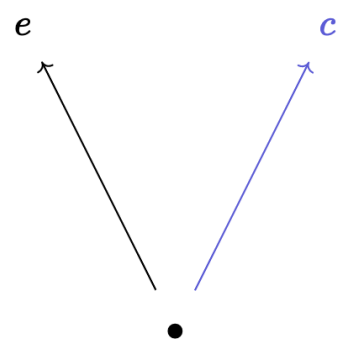
## Mode 1

- Option **a**
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- Option **c**
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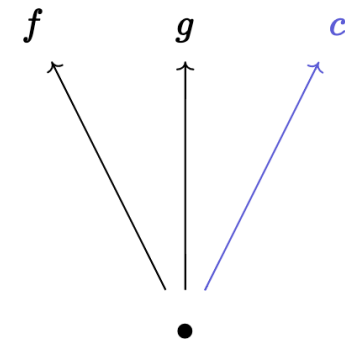
## Mode 2

- Option **e**
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## Mode 3

- Option **f**
- Option **g**
- Option **c**



# PF for mode-dependent dynamical systems: An Intuition

## Mode 1

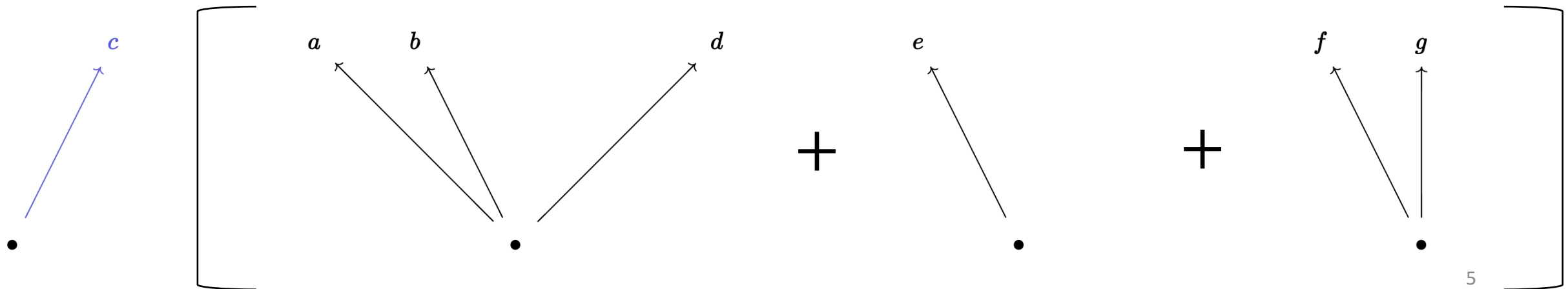
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## Mode 2

- Option **e**
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## Mode 3

- Option **f**
- Option **g**
- Option **c**



# Example: Happy Refrigerator

## “Add” (A) Mode

- Add drink
- Don't add drink

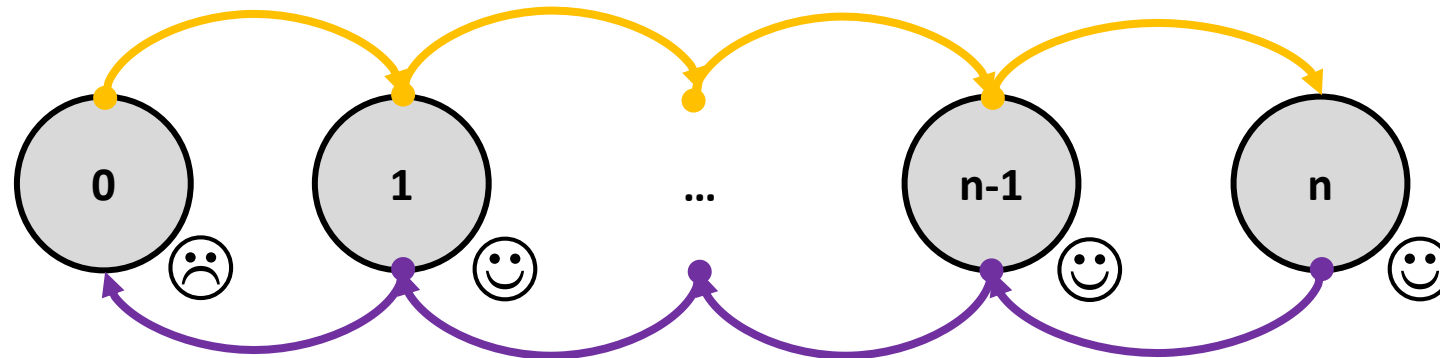
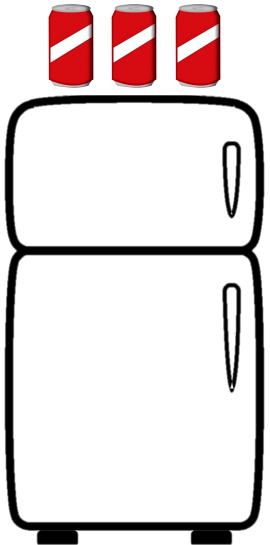
## “Take” (T) Mode

- Take drink
- Don't take drink

## “Add or Take” (AT) Mode

- Add drink, don't take
- Don't add, take drink
- Add drink, take drink
- Do nothing

$n$  := number of drinks




$$\text{😊 } y^{\text{AT}} + \text{☹️ } y^{\text{A}} + \text{😊 } y^{\text{T}}$$

# Finite Polynomials and Coalgebras in Catlab

```
16
17 mutable struct PolyDynam
18     p::FinPolyLabel
19     nStates::Int
20     modes::AbstractVector{Int}
21     behaviors::AbstractVector{Any}
22     s0::Int
23 end
24
25 function run(D::PolyDynam)
26     while true
27         position = D.modes[D.s0]
28         behavior = D.behaviors[D.s0]
29         output = subpart(D.p, position, :pos_label)
30         @printf("(State %s) %s\n\n", D.s0-1, output)
31
32         directions = incident(D.p, position, :pos)
33         options = subpart(D.p, directions, :dir_label)
34         @printf("Please select your choice for '%s':\n" String(Symbol(behavior)))
```

# Example: Happy Refrigerator

```
D = PolyDynam(p, # polynomial
              5, # number of states 
              [2, 1, 1, 1, 3], # position per state
              [add, add_and_take, add_and_take, add_and_take, take], # behavior
              2) # initial state index
```

```
julia> █
```

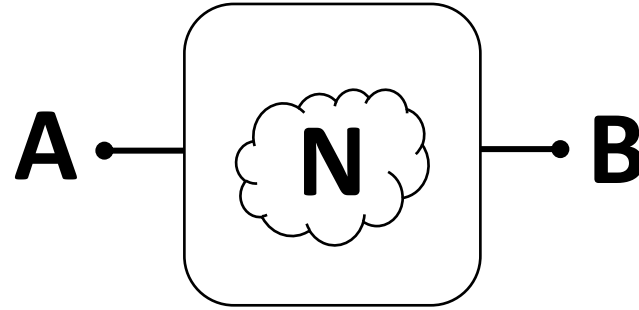


# Next Steps

Universal Programmable Machine and User Interface

# Universal programmable machine

*(A,B) Moore Machine*



$$N \times A \xrightarrow{\text{update}} N$$

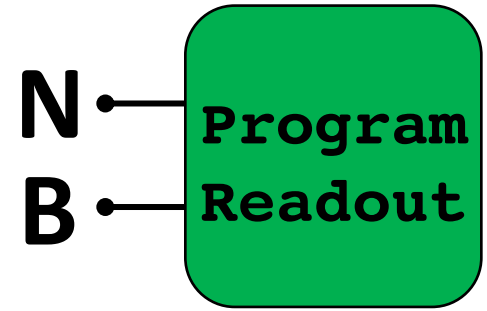
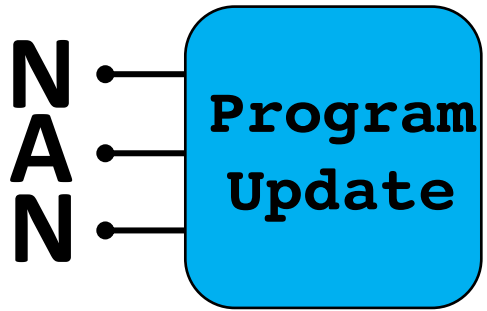
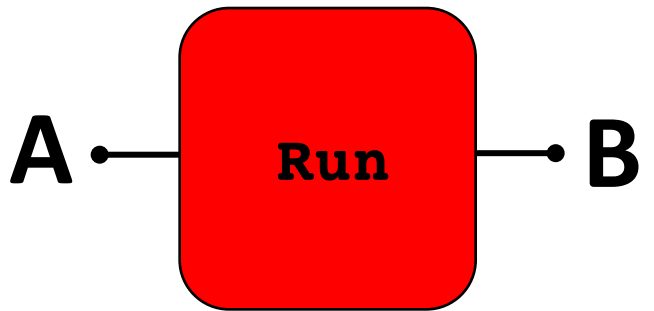
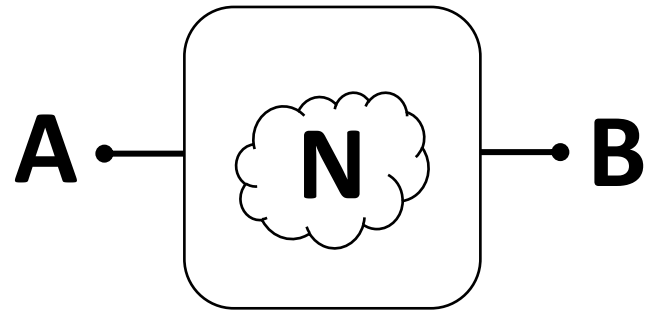
$$N \xrightarrow{\text{readout}} B$$

# Universal programmable machine

*(A,B) Moore Machine*

$$N \times A \xrightarrow{\text{update}} N$$

$$N \xrightarrow{\text{readout}} B$$

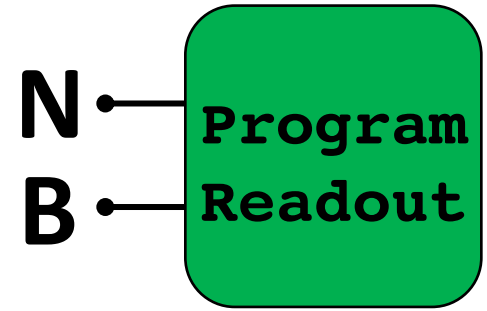
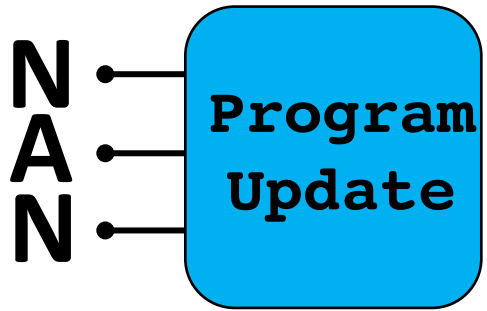
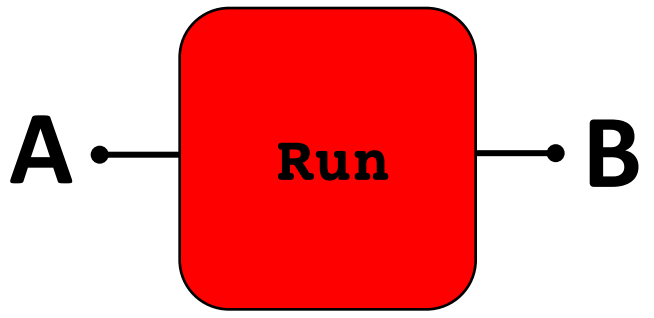
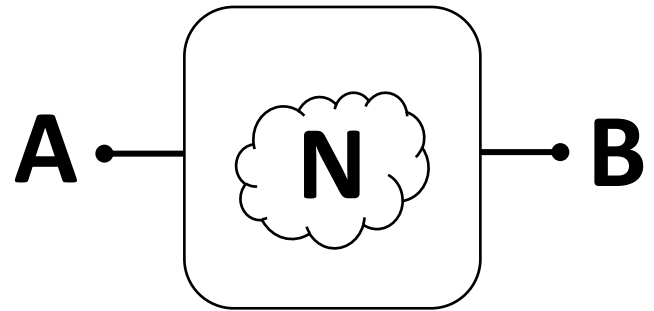


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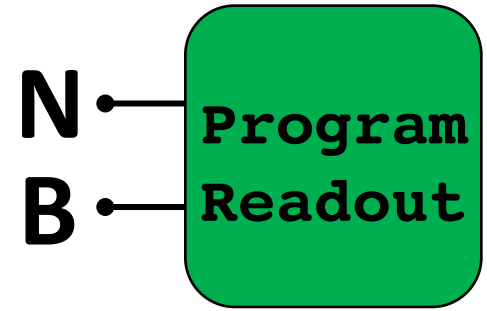
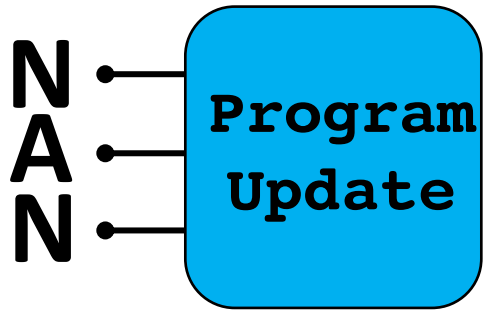
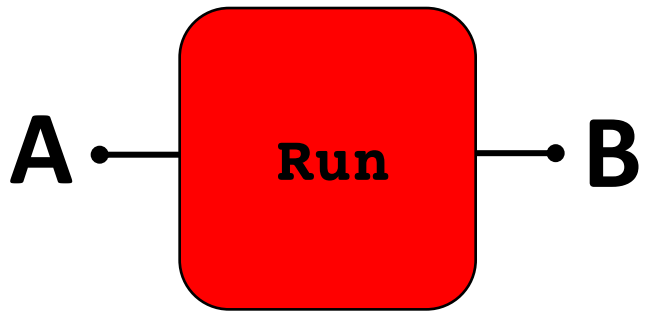
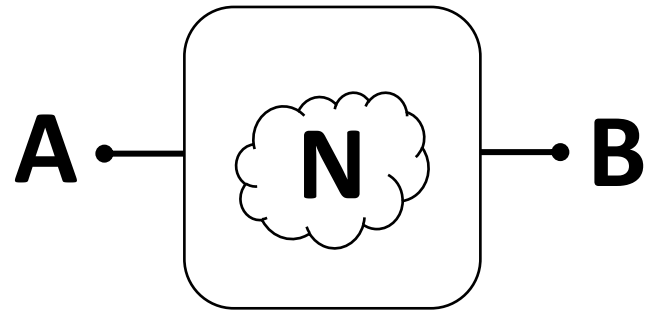


# Universal programmable machine

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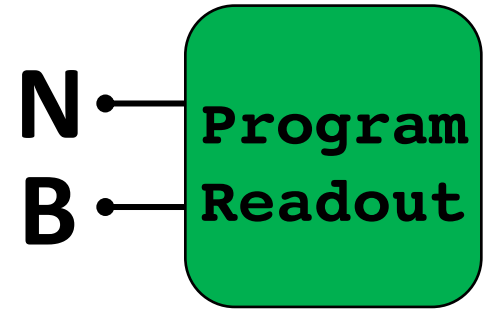
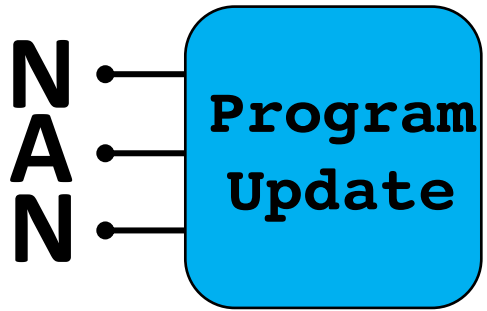
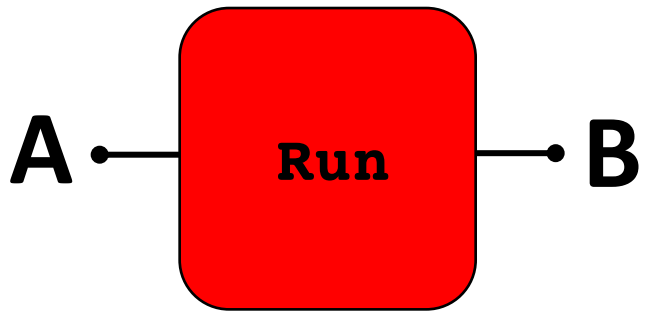
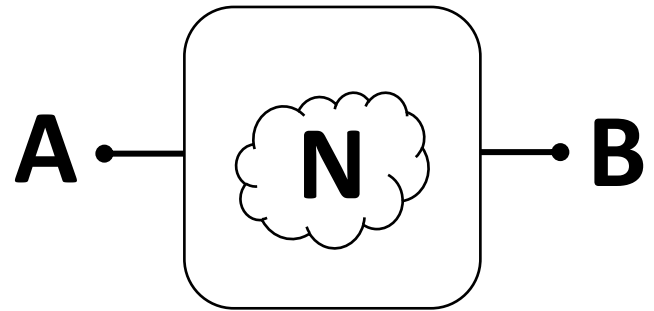
$$y(By^A + y^{NAN} + y^{NB})$$

# Universal programmable machine

*(A,B) Moore Machine*

$$N \times A \xrightarrow{\text{update}} N$$

$$N \xrightarrow{\text{readout}} B$$



$$y(By^A + y^{NAN} + y^{NB})$$

$$By^{A+1} + y^{NAN+1} + y^{NB+1}$$

A restricted class of polynomials

$$\sum_{m \in Mode} \left( \prod_{o \in Out_m} T_o \cdot y \sum_{s \in Sig_m} \prod_{i \in In_s} T_i \right)$$

A restricted class of polynomials

$$\sum_{m \in Mode} \left( \prod_{o \in Out_m} T_o \cdot y^{\sum_{s \in Sig_m} \prod_{i \in In_s} T_i} \right)$$



$$\mathbb{R} \cdot y^{\mathbb{R}} + \mathbb{Q} \times \mathbf{Bool} \cdot y^{\mathbb{R} + \mathbb{Z} \times \mathbb{Z}} + y + 1$$

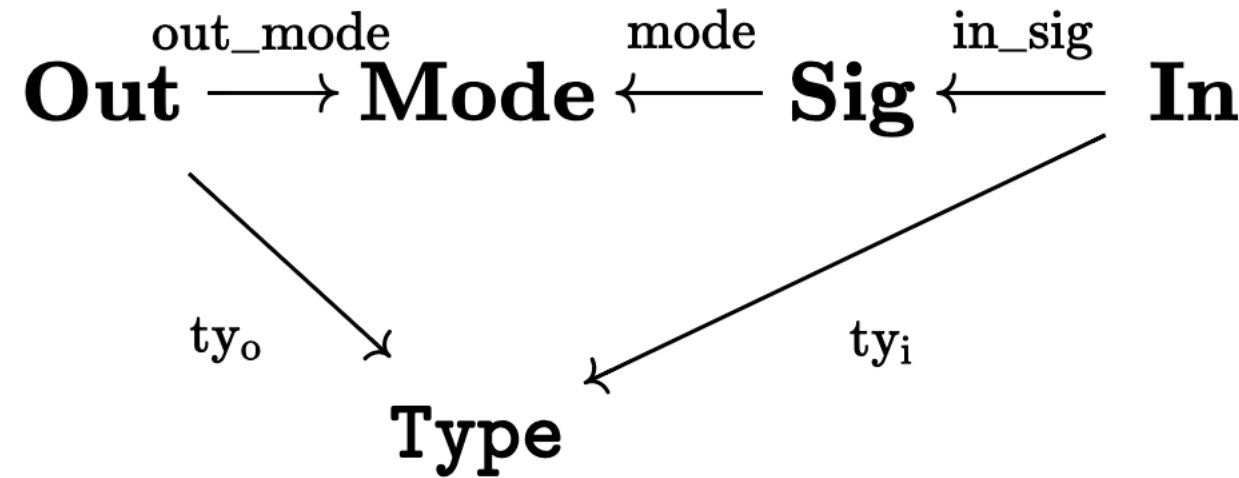


$$\mathbb{R}^{\mathbb{R}} \cdot y \quad y_{16}^{\mathbb{Z}^{\mathbb{Z}}}$$



# Attributed C-Sets

$$\sum_{m \in Mode} \left( \prod_{o \in Out_m} T_o \cdot y^{\sum_{s \in Sig_m} \prod_{i \in In_s} T_i} \right)$$



## Combinatorial data

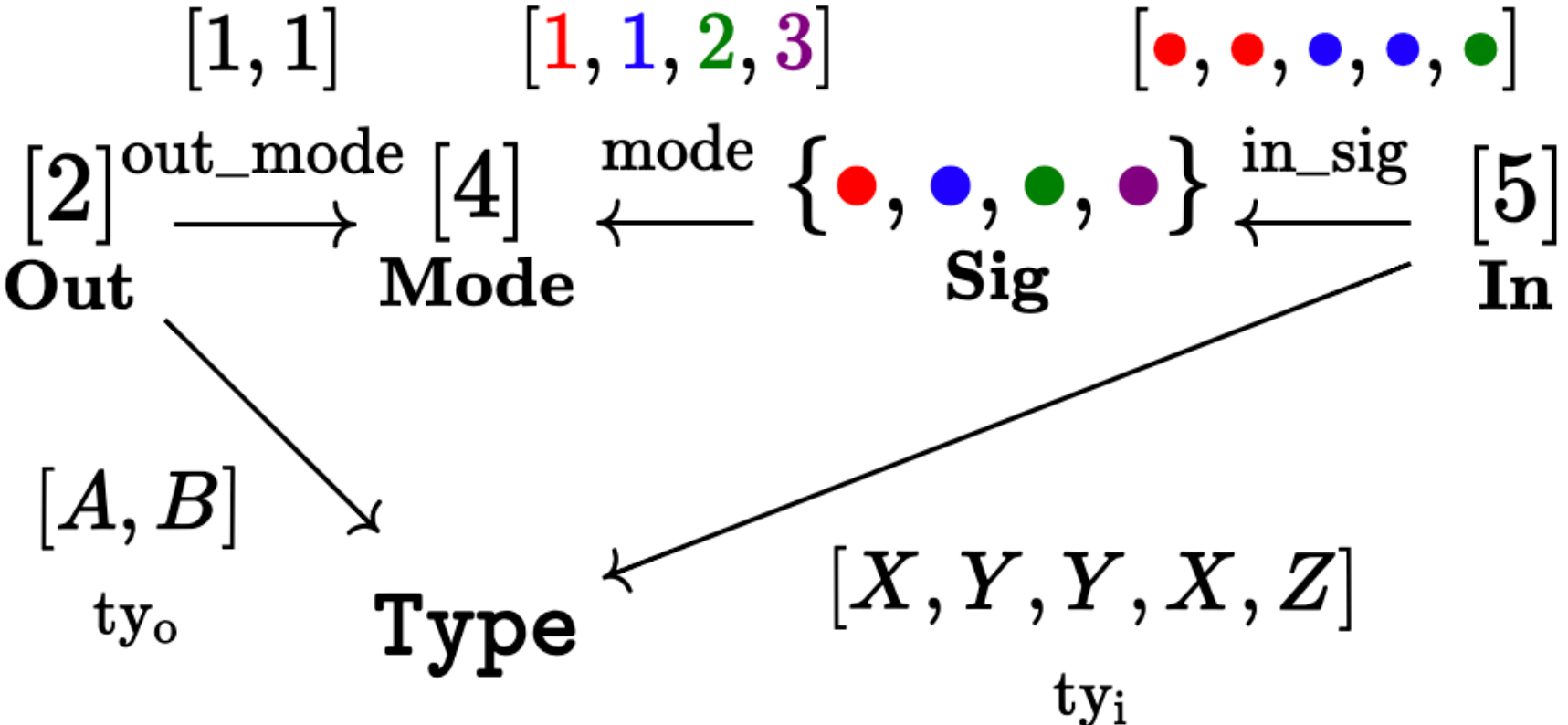
- Identifiers have no meaning
- Implementation: Skeleton of **FinSet**
- E.g. [2]

## Non-combinatorial data

- Preserved on the nose by morphisms
- Implementation: Arbitrary Julia types
- E.g. Bool

# Example instance

$$AB \cdot y^{XY+YX} + y^Z + y^1 + 1$$



# Back to middle school

```
In [2]: p = SumProdPoly{Symbol}([  
        [[:B]] => [[:S]],  
        [[:S]] => [[:S, :A]] ])  
show_(p)
```

$$S y^B + S \cdot A y^S$$

```
In [5]: show_(p*p)
```

$$S \cdot S y^{B+B} + S \cdot A \cdot S y^{S+B} + S \cdot S \cdot A y^{B+S} + S \cdot A \cdot S \cdot A y^{S+S}$$

```
In [4]: show_(p⊗p)
```

$$S \cdot S y^{B \cdot B} + S \cdot A \cdot S y^{S \cdot B} + S \cdot S \cdot A y^{B \cdot S} + S \cdot A \cdot S \cdot A y^{S \cdot S}$$

# Thank you

- Evan Patterson
- David Spivak
- Sophie Libkind
- Christian Williams

